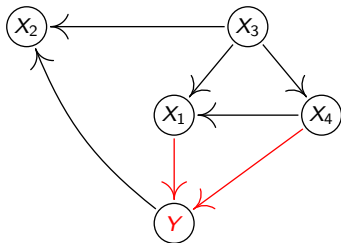


Two Ideas



Jonas Peters, University of Copenhagen
TUM-CPH-ETH Workshop
10 October 2022

VILLUM FONDEN



CARLSBERGFONDET



Members of the Copenhagen Causality Lab:



JEFF ADAMS



ALEXANDER MANGULAD CHRISTGAU

★ Christgau et al. (2022) 🚀



NICOLA GNECCO

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PHILLIP BREDAHL MOGENSEN

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★ Mogensen & Markussen (2021)



JONAS PETERS

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★ Thams et al. (2021) 🚀



NIKLAS PFISTER

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★ Saengkyongam et al. (2021) 🚀



SORAWIT SAENGYONGAM

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★ Saengkyongam et al. (2021) 🚀



NIKOLAJ THEODOR THAMS

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★ Thams* et al. (2022) 🚀



SEBASTIAN WEICHWALD

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★ Reisach et al. (2021) 🚀

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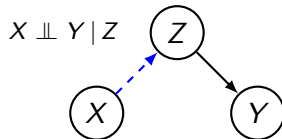
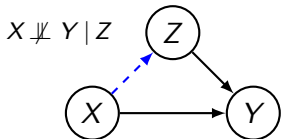
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 $\sup_{Q: \tau(Q) \in H_0^{\mathcal{P}}} \limsup_{n \rightarrow \infty} \mathbb{P}_Q(\psi_n(\mathbf{X}_n) = 1) \leq \alpha.$

Example: Conditional Independence Testing

$$X \perp\!\!\!\perp Y \mid Z \quad + \quad \text{known conditional } q^*(z|x) \quad \overset{\text{distr. shift}}{\longleftrightarrow} \quad X \perp\!\!\!\perp Y.$$

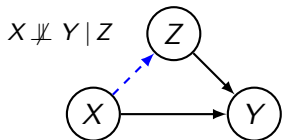
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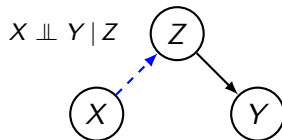


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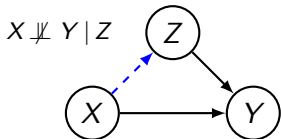
$X \not\perp\!\!\!\perp Y$ in $\tau(q)$



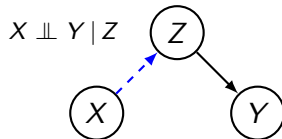
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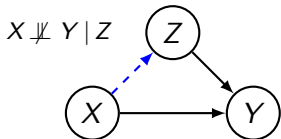
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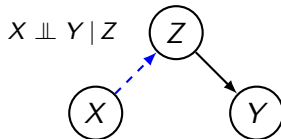
$$\tau(q)(x, y, z) := \underbrace{\frac{\phi(z)}{q^*(z|x)}}_{=: r(z,x) \text{ (known)}} \cdot q(x, y, z) \quad \text{for all } (x, y, z) \in \mathcal{Z}.$$

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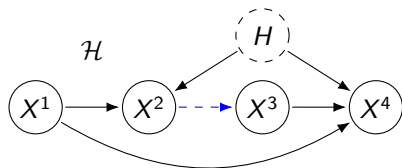
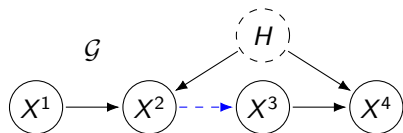
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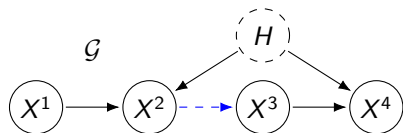
Thus: test $X \perp\!\!\!\perp Y$ in $\tau(q)$.

See also Candès et al. 2018, Berrett et al. 2020, Shah & Peters 2020.

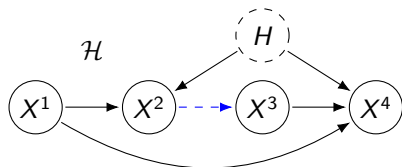
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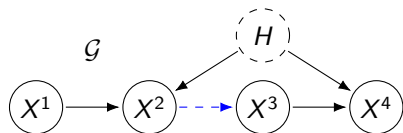
$X^1 \perp\!\!\!\perp X^4$ in $Q^{do(X^3:=N)}$



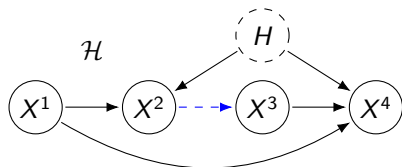
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Verma and Pearl 1991, Shpitser et al. 2012, Drton et al. 2009, Nowzohour et al. 2019

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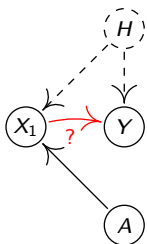
Verma and Pearl 1991, Shpitser et al. 2012, Drton et al. 2009, Nowzohour et al. 2019

Method in a nutshell:

1. Define weights $r(X_i) := p(X_i)/q(X_i)$.
2. Resample.
3. Apply existing test on target domain.

Thams, Saengkyongam, Pfister and Peters, arXiv 2021; see also SIR (Rubin, 1987; Smith and Gelfand, 1992)

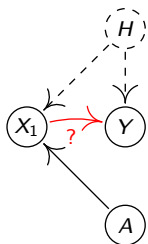
Instrumental Variables:



True model:

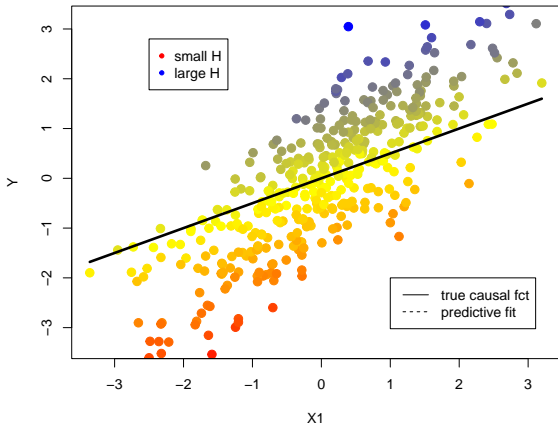
$$Y = \alpha^* X_1 + \gamma H + N_Y.$$

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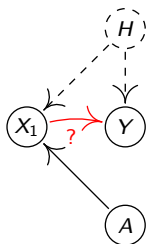


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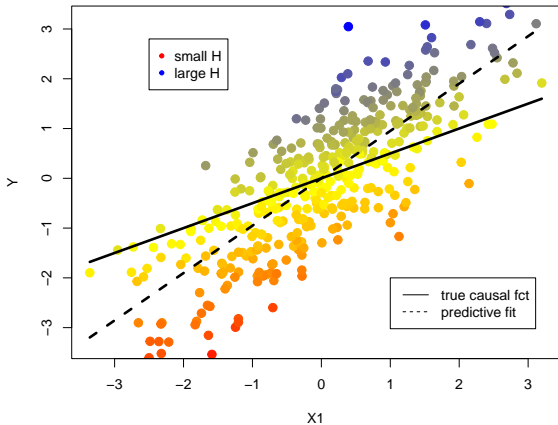


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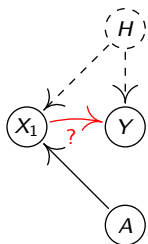


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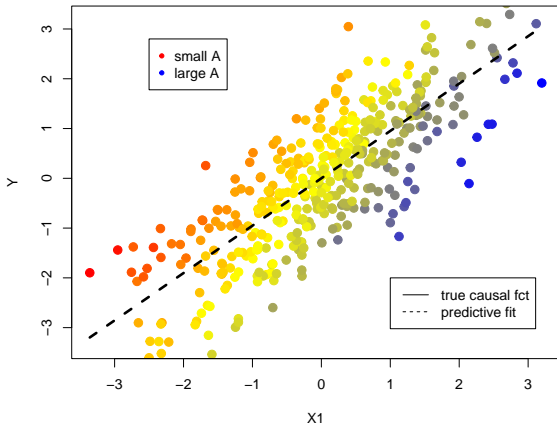


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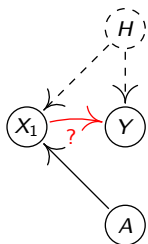


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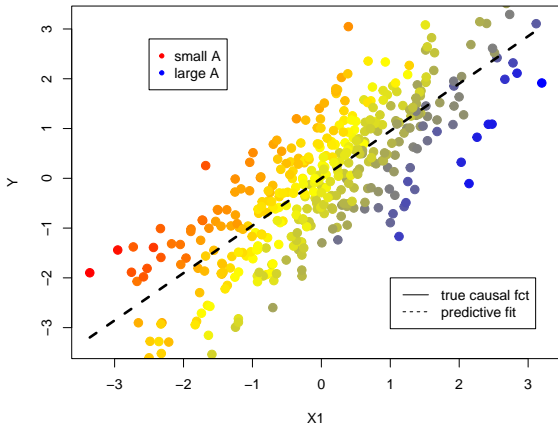


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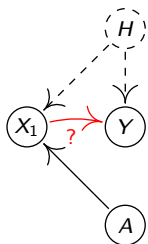
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Find α such that

$$\text{cov}[A, Y - \alpha X_1] = 0.$$



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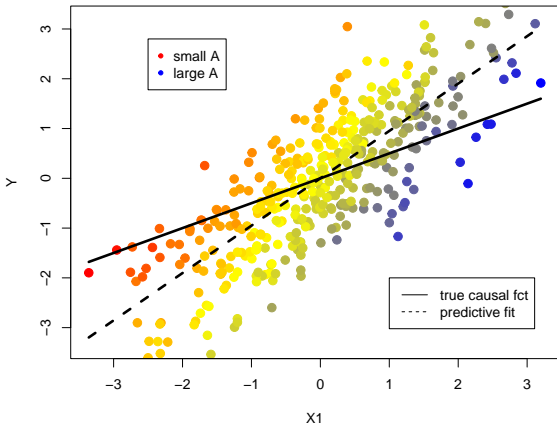
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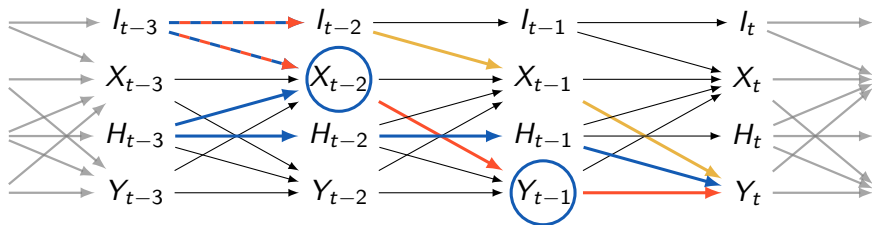
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IV: Anderson and Rubin 1949, Theil 1953, ...



Example: VAR processes.

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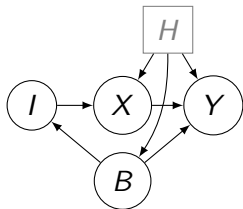
Here: $\text{cov}[I_{t-2}, Y_t - \beta^* X_{t-1}] \neq 0$ (see red path).

N. Thams, R. Nielsen, S. Weichwald, J. Peters:

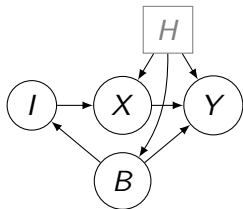
Identifying Causal Effects using Instrumental Time Series: NIV and Correcting for the Past, arXiv:2203.06056

Recall: conditional IV

Pearl 2009, Leo's PhD thesis 2021.

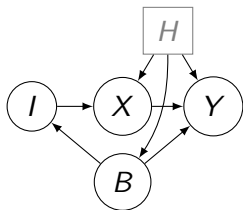


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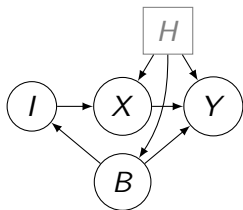


Linear SCM with DAG G and $Y = \beta^\top X + \gamma^\top W + \varepsilon$. Assume

- I and Y are d -sep by B in $G_{X \nrightarrow Y}$.
- $B \notin \text{DE}(X \cup Y)$.
- $E[\text{cov}(X, I|B)]$ has rank d_X .

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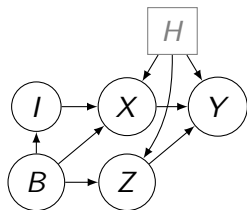
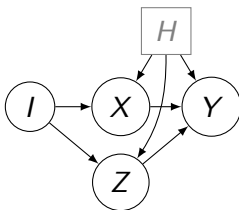
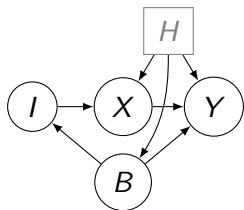
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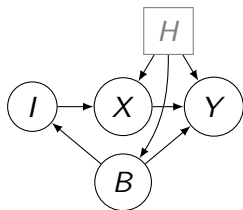
We write $\text{CIV}(I|B)$.

Interested in: $X \rightarrow Y$



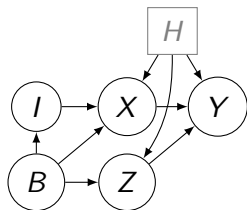
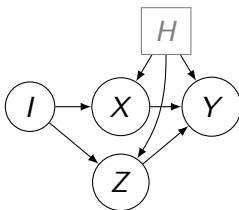
Left:

Interested in: $X \rightarrow Y$

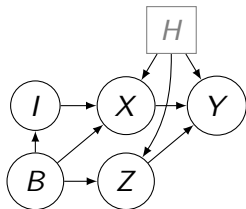
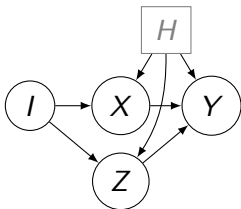
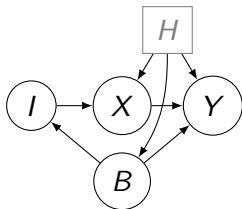


Left: $CIV(I|B)$

Middle:



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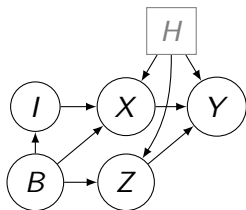
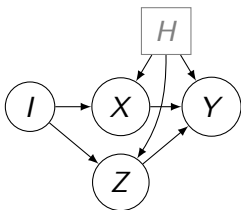
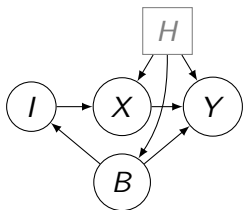


Left: $CIV(I|B)$

Middle: $NIV(I, Z)$

Right:

Interested in: $X \rightarrow Y$

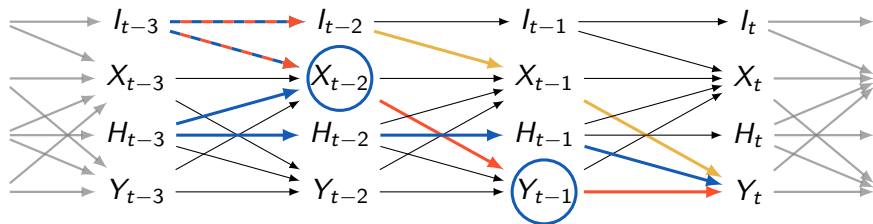


Left: $CIV(I|B)$

Middle: $NIV(I, Z)$

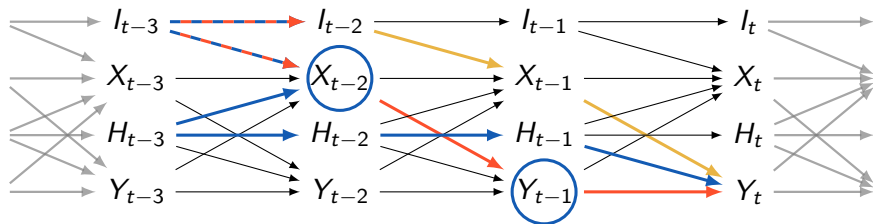
Right: $CIV(I|B)$ or $NIV(\{I, B\}, Z)$.

Example: VAR processes.



Here: $\text{cov}[I_{t-2}, Y_t - \beta^* X_{t-1}] \neq 0$ (see red path).

Example: VAR processes.

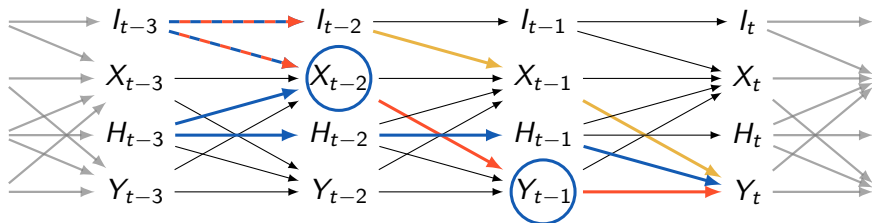


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- conditional IV

$$\text{CIV}(I_{t-2}, \{I_{t-3}, X_{t-2}, Y_{t-1}\}) \text{ or } \text{CIV}(I_{t-2}, I_{t-3})$$

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- conditional IV

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- nuisance IV

$$\text{NIV} \left(\begin{pmatrix} I_{t-2} \\ I_{t-3} \end{pmatrix}, Y_{t-1} \right), \text{ i.e., } \text{cov} \left[\begin{pmatrix} I_{t-2} \\ I_{t-3} \end{pmatrix} (Y_t - \beta^* X_{t-1} - \gamma Y_{t-1}) \right] = 0$$

N. Thams, R. Nielsen, S. Weichwald, J. Peters:

Identifying Causal Effects using Instrumental Time Series: NIV and Correcting for the Past, arXiv:2203.06056

Let M be a square matrix. There exists P such that $M = PJP^{-1}$, where

$$J = \text{diag}(J_{m_1}(\lambda_1), \dots, J_{m_k}(\lambda_k)), \quad J_{m_i}(\lambda) = \begin{pmatrix} \lambda & 1 & & \\ & \lambda & \ddots & \\ & & \ddots & \\ & & & \lambda \end{pmatrix} = \lambda I + N$$

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Properties:

- Eigenvalues of M = diagonal values of J
- Geom. multipl. of λ_i (in M) = # of Jordan blocks with λ_i
- Alg. multipl. of λ_i (in M) = sum of lengths of Jordan blocks with λ_i
- M is diagonalizable if geom. and alg. multiplicity coincide.
- $M^n = PJ^nP^{-1} = P \left(\sum_{i=0}^n \binom{n}{i} \lambda^{n-i} N^i \right) P^{-1}$.

Data-generating process: We consider a VAR system S where

$$S_{t+1} = AS_t + \epsilon_{t+1}$$

We assume that S is stable (eigenvalues within unit circle) and that ϵ is non-singular.

$$A = \begin{matrix} I \\ H \\ X \\ Y \end{matrix} \begin{pmatrix} \alpha_I & 0 & 0 & 0 \\ 0 & \alpha_H & 0 & 0 \\ \begin{bmatrix} \gamma \\ 0 \end{bmatrix} & \nu_X & \begin{bmatrix} \alpha_X & 0 \\ \beta & \alpha_Y \end{bmatrix} \end{pmatrix}$$

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Required for identifiability through NIV:

$$\Sigma := E \left\{ \begin{pmatrix} X_t \\ Y_t \end{pmatrix} (I_{t-1}, \dots, I_{t-d_X-1}) \right\} \in \mathbb{R}^{(d_X+1) \times (d_X+1)}$$

is full rank.

Consider the decomposition

$$M_{XY} = PJP^{-1}$$

with Jordan normal form

$$J = \text{diag}(J_{m_1}(\lambda_1), \dots, J_{m_k}(\lambda_k))$$

and let $a := P^{-1}M_I$. The following three statements are equivalent:

- 1 Σ is invertible.
- 2 The matrix $\begin{bmatrix} M_{XY}^0 M_I & M_{XY}^1 M_I & \dots & M_{XY}^{d_X} M_I \end{bmatrix}$ is invertible.
- 3 Different Jordan blocks have different eigenvalues and for all $q \in \{1, \dots, k\}$, the coefficient $a_{\sum_{i=1}^q m_i}$ is non-zero.

Summary

Testing under distributional shifts:

- Applies to many problems including cond. ind. tests, Verma constraints, model selection under covariate shift, (off-policy evaluations, two-sample testing) ...
- Black box method: resampling and test in the target domain.
- Comes with theoretical guarantees.

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VAR-IV:

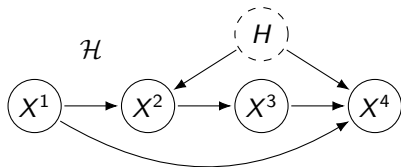
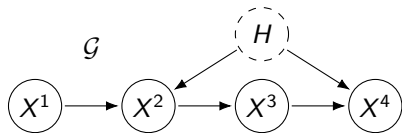
- Nuisance IV yields different identifiability results than Conditional IV.
- Both can be applied to VAR-IV settings (even multivariate).
- Identifiability results are similar to those in systems of ordinary differential equations.

S. Saengkyongam, N. Thams, JP, N. Pfister: *Invariant Policy Learning: A Causal Perspective*, arXiv 2021

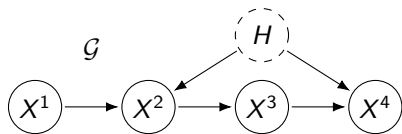
N. Thams, R. Nielsen, S. Weichwald, JP: Identif. Causal Effects using Instr. TS: Nuisance IV and Corr. for the Past, arXiv 2022

N. Thams, S. Saengkyongam, N. Pfister, JP: *Statistical Testing under Distributional Shifts*, arXiv 2021

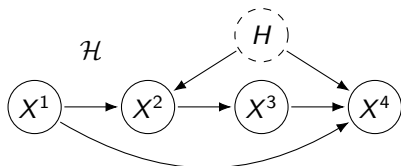
Example: Dormant independences



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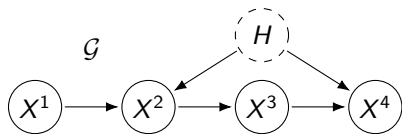


$X^1 \perp\!\!\!\perp X^4$ in $Q^{do(X^3:=N)}$

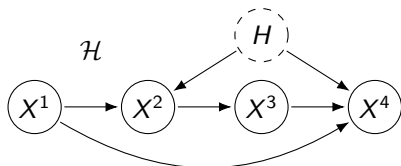


$X^1 \not\perp\!\!\!\perp X^4$ in $Q^{do(X^3:=N)}$.

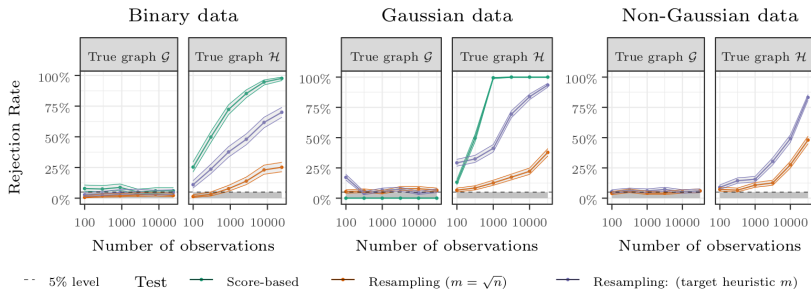
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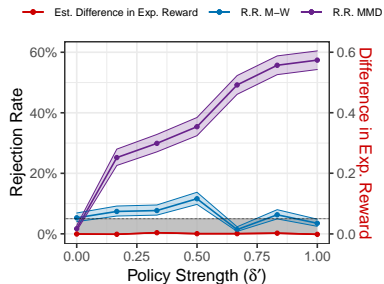
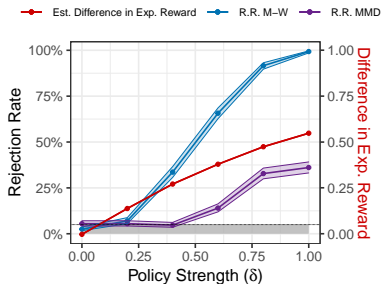


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Verma and Pearl 1991, Shpitser et al. 2012

Off-policy evaluation:



Example: Model Selection under Covariate Shift

Training distribution: $q_{\text{train}}(x, y) = q_{\text{train}}^*(x)q(y|x)$

Test distribution: $p_{\text{test}}(x, y) = p_{\text{test}}^*(x)q(y|x)$

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Held out data (have): $D_{\text{heldout}} = \{(x_1, y_1), \dots, (x_n, y_n)\} \sim q_{\text{train}}$

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Above framework allows to test, e.g.,

$$H_0 : \mathbf{E}_{D^{sh} \sim p_{\text{test}}} [S(D^{sh}, \hat{f}_1) - S(D^{sh}, \hat{f}_2)] \leq 0.$$

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General and easy-to-use method based on resampling and existing test:

1. Resample m data points with weights

$$w_{(i_1, \dots, i_m)} \propto \begin{cases} \prod_{\ell=1}^m r(X_{i_\ell}) & \text{if } (i_1, \dots, i_m) \text{ is distinct and} \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

2. Apply existing test φ_m from target domain to resampled data.

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Theorem (Thams et al., 2021)

Pointwise asymptotic level holds if:

A1 φ_m has pointwise asymptotic level,

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A3 for all $Q \in \tau^{-1}(H_0)$, it holds that $\mathbf{E}_Q[r(X_i)^2] < \infty$.

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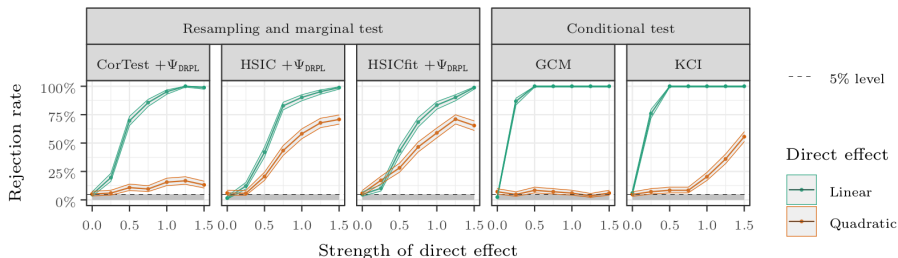
A similar statement holds if r needs to be estimated.

N. Thams, S. Saengkyongam, N. Pfister, JP: *Statistical Testing under Distributional Shifts*, arXiv 2021
cf. SIR, see Rubin (1987) and Smith and Gelfand (1992)

Example: Conditional Independence Testing

We sample $n = 150$ observations from

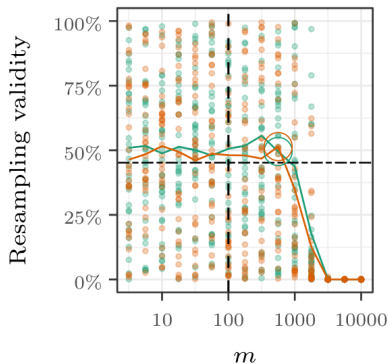
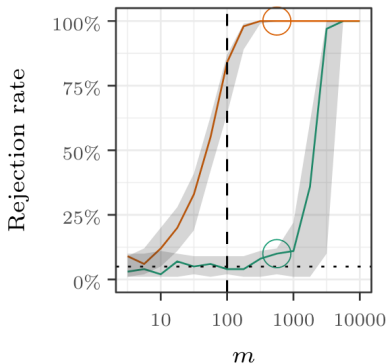
$$X := \text{GaussianMixture}(-2, 2) \quad Z := -X^2 + \epsilon_Z \quad Y := \sin(Z) + \theta X^\tau + \epsilon_Y,$$



Gretton et al. 2008, Zhang et al. 2011, Shah & Peters 2020

Example: Conditional Independence Testing

How can we choose m ?



—●— null —●— alternative - - $m = \sqrt{n}$ or $\sigma^2 = 2(\sigma_{\varepsilon_Z}^2 - \sigma_X^2)$...

using a test by Jitkrittum et al., 2020