Anytime-Valid Tests of Conditional Independence under Model-X

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Peter Grünwald, Rianne de Heide, and Wouter Koolen (2022+). "Safe Testing". In: *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*. To appear. Preprint: arXiv:1906.07801

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A process  $S_n = S_n(D^n)$ ,  $n \in \mathbb{N}$ , is called e-process if

 $S_n \geq 0, \ n \in \mathbb{N}, \quad \mathbb{E}_P[S_{\tau}] \leq 1 \ \text{ for all stopping times } au, \ P \in \mathcal{H}_0.$ 

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Implications:

▶ 
$$P(\exists n: S_n \ge 1/\alpha) \le \alpha$$
 for all  $P \in \mathcal{H}_0, \alpha \in (0, 1)$ ,  
▶  $p_n = 1/(\max_{i=1,...,n} S_i)$ , is an anytime-valid p-value.

Wald's (1947) sequential probability ratio test is anytime-valid:

Let  $D_i$  have density  $f_{0,i}$  under the null hypothesis and  $f_{1,i}$  under the alternative. Under independence of  $(D_i)_{i \in \mathbb{N}}$ ,

$$S_n = \prod_{i=1}^n rac{f_{1,i}(D_i)}{f_{0,i}(D_i)}$$
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We will need something more general:

If  $E_n(D^n) \ge 0$  and  $\mathbb{E}_P[E_n(D^n) \mid D^{n-1}] \le 1$  for all n, then

$$S_n = \prod_{i=1}^n E_i(D^i)$$
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How to construct e-processes for testing conditional independence in a general setting?

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What are "good" e-processes for this problem?

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- What are "good" e-processes for this problem?
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Everything in the model-X setting (Candès et al., 2018).

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#### Model-X and conditional randomization test

"a glorified randomized experiment where we know the propensity score"

Assumptions: observations  $D_n = (X_n, Y_n, Z_n)$ ,  $n \in \mathbb{N}$ , are i.i.d. and the distribution of X given Z is known,

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Conditional randomization test (CRT):

- ► T(X<sup>n</sup>, Y<sup>n</sup>, Z<sup>n</sup>) a function such that T is large if X and Y are conditionally dependent,
- ▶ simulate  $ilde{X}_j^n \sim Q_{Z^n}^n$ , j = 1, ..., M, and define

$$ho = rac{1 + \sum_{j=1}^M \mathbbm{1}\{T( ilde{X}^n_j, Y^n, Z^n) \geq T(X^n, Y^n, Z^n)\}}{1 + M}$$

### Anytime-valid tests of conditional independence

For a single D = (X, Y, Z) and any function h > 0,

$$E_h(D) = \frac{h(X, Y, Z)}{\int h(x, Y, Z) \, dQ_Z(x)}$$

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Define the e-process

$$S_n = S_n(D^n) = \prod_{i=1}^n \frac{h_i(X_i, Y_i, Z_i)}{\int h_i(x, Y_i, Z_i) \, dQ_{Z_i}(x)},$$

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where  $h_i$  may depend on  $D^{i-1}$ .

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 $S_n$  is "growth rate optimal" (GRO) (Grünwald, de Heide, and Koolen, 2022+) under the alternative hypothesis  $\tilde{P}$  if it

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Result: If (X, Y, Z) admit a density f, then the GRO  $S_n$  is obtained for  $h_i(x, y, z) = f_{Y|X,Z}(Y_i | X_i, Z_i)$ , and

$$S_n = \prod_{i=1}^n \frac{f_{Y|X,Z}(Y_i \mid X_i, Z_i)}{f_{Y|Z}(Y_i \mid Z_i)}.$$



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 $\mathbb{E}_{f}[\log(S_{n})] = nI_{f}(X; Y \mid Z) \text{ (conditional mutual information)},$ 

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The same test statistic, f<sub>Y|X,Z</sub>, yields Neyman-Pearson optimal CRT (Katsevich and Ramdas, 2020).

In practice, f is estimated sequentially.

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In practice, f is estimated sequentially.

• Construct estimator  $\hat{f}^{i}_{Y|X,Z}$  based on data  $D^{i}$ , and set

$$S_n = \prod_{i=1}^n \frac{\hat{f}_{Y|X,Z}^{i-1}(Y_i \mid X_i, Z_i)}{\int \hat{f}_{Y|X,Z}^{i-1}(Y_i \mid x, Z_i) \, dQ_{Z_i}(x)},$$

• or  $\hat{f}_{X|Y,Z}^{i}$ , and with the density  $q_{X|Z}$  of  $Q_z$ , set

$$S_n = \prod_{i=1}^n \frac{\hat{f}_{X|Y,Z}^{i-1}(X_i \mid Y_i, Z_i)}{q_{X|Z}(X_i \mid Z_i)}.$$

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#### Robustness

Like the CRT, the proposed tests are valid for any choice of the functions  $h_i$  or estimators  $\hat{f}^i_{Y|X,Z}$ .

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Like the CRT, the proposed tests are valid for any choice of the functions  $h_i$  or estimators  $\hat{f}^i_{Y|X,Z}$ .

If the model-X assumption is violated and only approximations  $\hat{Q}_z$  of  $Q_z$  are available, then

$$P\left(\exists n \leq N \colon S_n \geq 1/\alpha \middle| Y^N, Z^N\right) \leq \alpha + d_{\mathrm{TV}}(Q^N_{Z^N}, \hat{Q}^N_{Z^N}), \ N \in \mathbb{N},$$

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where  $d_{\mathrm{TV}}$  is the total variation distance.

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where  $d_{\mathrm{TV}}$  is the total variation distance.

Same bound is known for the CRT (Berrett et al., 2020) without sequential testing (no " $\exists n \leq N$ ").

### Sanity check: logistic regression

Assume that  $Y \in \{0,1\}$  with probabilities

$$p_{\theta}(y \mid X, Z) = \frac{\exp(y(\beta^{\top}X + \gamma^{\top}Z))}{1 + \exp(\beta^{\top}X + \gamma^{\top}Z)},$$

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with parameter vector  $\theta = (\beta, \gamma)$ .

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with parameter vector  $\theta = (\beta, \gamma)$ .

Estimate  $\theta$  sequentially with maximum likelihood method.

Result: if (X, Z) ∈ ℝ<sup>p</sup> × ℝ<sup>q</sup> is subgaussian, then the corresponding test has asymptotic power one if β ≠ 0,

$$S_n = \exp\left(nI(X; Y \mid Z) + r_n\right), \ r_n/n \rightarrow 0 \text{ a.s.}$$

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Simulations:

(X, Z) ∈ ℝ × ℝ<sup>q-1</sup> with multivariate normal distribution
 logistic model for Y

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Other tests:

- Non-sequential CRT and likelihood ratio test
- Universal inference running maximum likelihood (Wasserman, Ramdas, and Balakrishnan, 2020)



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Preprint on arXiv:

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