

The Projected Covariance Measure for model-free variable significance testing

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Outline

- Formalising variable significance
- Regression-based variable significance tests
- The Projected Covariance Measure (PCM)
- Numerical results

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Introduction

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When the linear model is misspecified, we might either wrongly declare X to be important or unimportant, and similar issues arise from other tests based on parametric models.

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The alternative, conditional mean dependence, may be characterised by the property that X improves the prediction of Y in a mean-squared error sense, given knowledge of Z .

Contrasting with conditional independence

A more common model-free hypothesis is that of conditional independence; we say that Y and X are **conditionally independent** given Z and write $Y \perp\!\!\!\perp X \mid Z$ if

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This also means we are faced with the same statistical limitations as when testing conditional independence.

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As a consequence of this result, we know that domain knowledge is required to select a conditional independence test tailored to the problem at hand.

The Generalised Covariance Measure (GCM)

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For $X \in \mathbb{R}$, set

$$L_i := \{Y_i - \hat{m}_{Y|Z}(Z_i)\}\{X_i - \hat{m}_{X|Z}(Z_i)\}$$
$$\text{GCM}_{Y,X|Z} := \sqrt{n} \frac{\frac{1}{n} \sum_{i=1}^n L_i}{\left\{ \frac{1}{n} \sum_{i=1}^n (L_i - \bar{L})^2 \right\}^{1/2}}.$$

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Under conditions $\text{GCM}_{Y,X|Z} \xrightarrow{d} \mathcal{N}(0, 1)$ under the null.

The primary requirement is that

$$\frac{1}{n} \sum_{i=1}^n \{m_{Y|Z}(Z_i) - \hat{m}_{Y|Z}(Z_i)\}^2 \cdot \frac{1}{n} \sum_{i=1}^n \{m_{X|Z}(Z_i) - \hat{m}_{X|Z}(Z_i)\}^2 = o_P(n^{-1}).$$

Power of the GCM

As the GCM is a normalised version of $\mathbb{E}\text{Cov}(Y, X | Z)$, we only have power when $\mathbb{E}\text{Cov}(Y, X | Z) \neq 0$, which is not always the case when $\mathbb{E}(Y | X, Z) \neq \mathbb{E}(Y | Z)$.

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Consider $(X, Z, \varepsilon) \sim \mathcal{N}_3(0, I)$ and $Y = X^2 + \varepsilon$. Here, $\text{Cov}(Y, X | Z) = 0$ so $\mathbb{E}\{\text{Cov}(Y, X | Z)\} = 0$ hence the GCM is powerless.

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We would like a test that:

- relies primarily on user-chosen machine learning methods performing sufficiently well (i.e. restricts the null in this fashion);
- has power against a more diverse set of alternatives.

Estimating the mean squared difference in regression functions

Williamson et al. [2021a] propose to estimate

$$\tau := \mathbb{E}[\{\mathbb{E}(Y | X, Z) - \mathbb{E}(Y | Z)\}^2] = \mathbb{E}[\{Y - \mathbb{E}(Y | Z)\}^2] - \mathbb{E}[\{Y - \mathbb{E}(Y | X, Z)\}^2]$$

via

$$\hat{\tau} := \frac{1}{n} \sum_{i=1}^n \{Y_i - \hat{m}_{Y|Z}(Z_i)\}^2 - \frac{1}{n} \sum_{i=1}^n \{Y_i - \hat{m}_{Y|X,Z}(X_i, Z_i)\}^2.$$

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Williamson et al. [2021b] propose a variant involving sample-splitting, but this approach sacrifices power.

An alternative approach

Our approach is based on the following characterisation of conditional mean independence:

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Consider the following oracular test statistic. Set $L_i^* := \{Y_i - \mathbb{E}(Y_i | Z_i)\}f(X_i, Z_i)$ and

$$T^* := \frac{\frac{1}{\sqrt{n}} \sum_{i=1}^n L_i^*}{\sqrt{\frac{1}{n} \sum_{i=1}^n (\tilde{L}_i^*)^2}},$$

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$\mathbb{E}L_i^* / \sqrt{\text{Var}(\tilde{L}_i^*)} \approx \mathbb{E}T^*$ is maximised under the alternative via

$$f(X, Z) := \frac{\mathbb{E}(Y | X, Z) - \mathbb{E}(Y | Z)}{\text{Var}(Y | X, Z)} =: \frac{h(X, Z)}{v(X, Z)}.$$

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- 3 Set $T := \text{GCM}_{Y, \hat{f}(X, Z)|Z}$, computed on \mathcal{D}_1 , and reject when $T > z_{1-\alpha}$.

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$h(X, Z) = 0$ under the null, so both the numerator and denominator of the test converges to 0!

Despite this, the primary condition for Type I error control is

$$\frac{1}{n} \sum_{i=1}^n \{m_{Y|Z}(Z_i) - \hat{m}_{Y|Z}(Z_i)\}^2 \cdot \frac{1}{n\sigma^2} \sum_{i=1}^n \{m_{\hat{f}|Z}(Z_i) - \hat{m}_{\hat{f}|Z}(Z_i)\}^2 = o_P(n^{-1}),$$

where $\sigma := \text{Var}(\hat{f}(X, Z) - m_{\hat{f}|Z}(Z) | \hat{f})$.

Power of the PCM

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By employing additional sample-splitting as in Newey and Robins [2018], setting $\hat{v} \equiv 1$ for simplicity and using regression splines for each of our regression, we obtain (under conditions) that

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- $T \xrightarrow{d} \mathcal{N}(0, 1)$ under the null;
- The PCM has uniform power against alternatives with

$$\tau \gtrsim n^{-4s/(4s+d_X+d_Z)}.$$

The PCM is thus **minimax optimal** in this setting.

Numerical results

Let $Z \in \mathbb{R}^7$, $\varepsilon, \xi \in \mathbb{R}$ be independent, with $(Z, \varepsilon, \xi) \sim \mathcal{N}_9(0, I)$ and consider the null setting where

$$X = \sin(2\pi Z_1)(1 + Z_2) + \xi, \quad Y = \sin(2\pi Z_1)(1 + Z_2) + \varepsilon.$$

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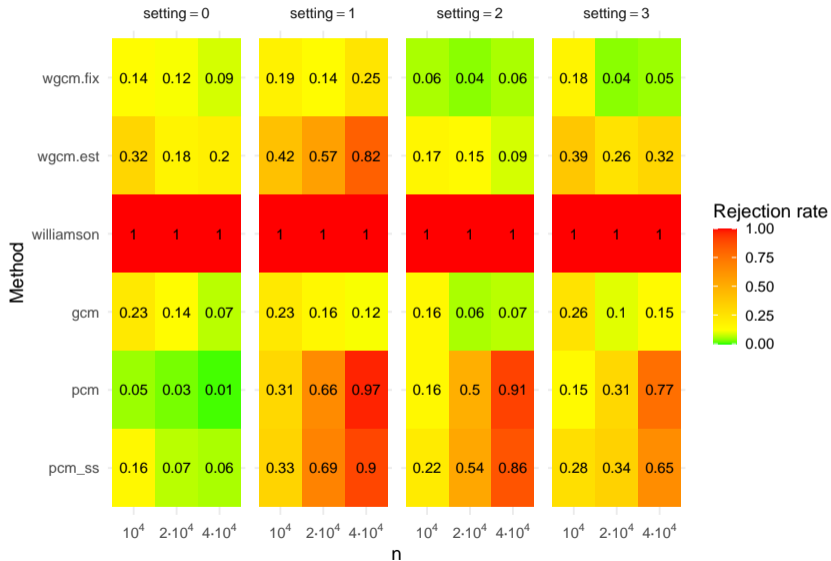
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Consider also alternative settings, that are modifications of the null, where

- 1 $\mathbb{E}\text{Cov}(Y, X | Z) = 0$ but $\text{Cov}(Y, X | Z) \neq 0$ (additive effect);
- 2 $\text{Cov}(Y, X | Z) = 0$ but $\mathbb{E}(Y | X, Z) \neq \mathbb{E}(Y | Z)$;
- 3 $\mathbb{E}\text{Cov}(Y, X | Z) = 0$ but $\text{Cov}(Y, X | Z) \neq 0$ (interaction effect);

PCM simulations using ranger



Conclusion

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Thank you for listening.

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