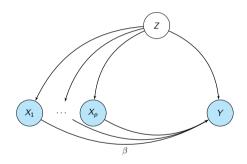
### Adjusting for Multi-Cause Confounding

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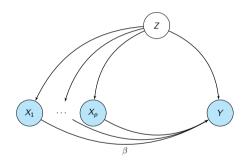
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## The Confounding Model



- i.i.d. samples of p treatments  $X_i$  and a response Y.
- Goal: Estimate the treatment effect of X on Y.
- Problem: There is an unobserved confounder Z.
- Assumption: Treatments are non-adjacent.
- Assumption: Z is a "multi-cause" confounder.
- Assumption: Additive treatment effects  $\beta$ .

#### The Intuition



- If Z were measured, we could regress  $Y = \hat{\beta}_j X_j + \hat{g}(Z)$  for any j of interest.
- If  $f(x) = \arg \max_{z} p(Z = z | X = x)$  were known, then we could plug in  $\hat{Z} = f(X)$ .
- Since X are assumed conditionally independent given Z, maybe we can learn  $\hat{f}$  from X.
- Together, the regression is  $Y = \hat{\beta}_j X_j + \hat{g}(\hat{f}(X)).$

Recent related papers include:

- Wang and Blei (2019): Advocate non-parametric estimation of Z, but give no finite-sample guarantees.
- Ogburn et al. (2020) and Grimmer et al. (2020): Critical response.
- Ćevid et al. (2020): A spectral transform and LASSO-based approach.

# Step 1: Learn $\hat{f}$ by Tensor Decomposition

- Modeling choice: Assume Z is discrete in  $\{1, ..., K\}$ .
- Partition X into thirds:  $X = (X_i, X_j, X_k)$ .
- By conditional independence,

$$\mathbb{E}[X_i \otimes X_j] = \sum_{z=1}^{K} \omega^{(z)} \mu_i^{(z)} \otimes \mu_j^{(z)}$$
$$\mathbb{E}[X_i \otimes X_j \otimes X_k] = \sum_{z=1}^{K} \omega^{(z)} \mu_i^{(z)} \otimes \mu_j^{(z)} \otimes \mu_k^{(z)}$$

- Kruskal's Theorem tells us  $\omega^{(z)}$  and  $\mu^{(z)}$  are (generically) identifiable.
- We can learn  $\mu^{(z)}$  and  $\omega^{(z)}$  with provable sample complexities in p and K. (Anandkumar et al., 2014) (Guo et al., 2022)

## Step 2: Latent Labeling

- Suppose estimates  $\hat{\mu}^{(z)}$  of  $\mu^{(z)}$  satisfy  $\|\hat{\mu}^{(z)} \mu^{(z)}\|_2 < \epsilon$ .
- Simplest labeling algorithm: pick the nearest mean!

$$\hat{Z} = rg \min_{z} \|X - \hat{\mu}^{(z)}\|_2$$



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• Bound the mislabeling rate with standard concentration inequalities:

$$\begin{split} \mathbb{P}[\hat{Z} = 2|Z = 1] &\leq \mathbb{P}\Big[ \left\| X - \hat{\mu}^{(2)} \right\|_{2} < \left\| X - \hat{\mu}^{(1)} \right\|_{2} \Big| Z = 1 \Big] \\ &= \mathbb{P}\Big[ (X - \hat{\mu}^{(1)})^{T} (\hat{\mu}^{(1)} - \hat{\mu}^{(2)}) < -\frac{1}{2} \left\| \hat{\mu}^{(1)} - \hat{\mu}^{(2)} \right\|_{2}^{2} \Big| Z = 1 \Big] \\ &\leq \frac{\left( \left\| \mu^{(1)} - \mu^{(2)} \right\|_{3} + 2\epsilon \right)^{2}}{\left( \left\| \mu^{(1)} - \mu^{(2)} \right\|_{2} - \epsilon \right)^{4}} \left\| \sigma^{(1)} \right\|_{3} \end{split}$$

• Decreasing in p for fixed  $\hat{\mu}$ ; rate depends on true separation in means.

## Step 3: OLS with Measurement Error

- Suppose  $\mathbb{P}[\hat{Z} = z' | Z = z] \leq \zeta$  for any distinct z, z'.
- Consider the OLS estimator  $\hat{\beta}_j^{\text{OLS}} = \frac{\hat{\mathbb{E}Cov}[X_j, Y|\hat{Z}]}{\hat{\mathbb{E}Var}[X_j|\hat{Z}]}.$

$$\left| \hat{\beta}_{j}^{\text{OLS}} - \hat{\beta}_{j} \right| \leq \underbrace{\left| \hat{\beta}_{j}^{\text{OLS}} - \hat{\beta}_{j}^{\text{oracle}} \right|}_{\leq O(K\sqrt{\zeta}) \to 0} + \left| \hat{\beta}_{j}^{\text{oracle}} - \beta_{j} \right|$$

with probability 
$$1 - \exp\left\{-rac{N_2}{8bK}
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 if  $K\sqrt{\zeta} \to 0$  and  $\omega_z \geq \frac{1}{bK}$ .

- Since  $\hat{\beta}_i^{\text{oracle}} \beta_j$  is unbiased and asymptotically (with respect to  $N_2$ ) normal:
  - We have consistency under the above conditions.
  - We have asymptotic normality with oracle variance if further  $K\sqrt{N_2\zeta} \rightarrow 0$ .

Suppose for all z there exist a, b such that  $\|\mu^{(z)} - \mu^{(z')}\|_2^2 \ge ap$  and  $\omega_z \ge \frac{1}{bK}$ .

- Given  $O(k^3/\delta)^*$  or  $O(p^2/\delta)$  samples, we can learn  $\mu^{(z)}$  to  $O(\sqrt{p})$  with probability  $1 \delta$ . (Anandkumar et al., 2014; Guo et al., 2022)
- This gives us mislabeling probabilities  $\zeta$  of O(1/p).
- Given  $O(K \log \frac{1}{\delta})$  additional samples, the bias for any  $\hat{\beta}_j^{OLS}$  is  $O(K/\sqrt{p})$  with probability  $1 2\delta$ .

#### Discussion

- We have a flexible 3 step pipeline.
  - Better tensor decomposition methods for step 1?
  - Sub-Gaussian bounds for step 2?
  - Nonlinear mechanism in step 3?
  - Extend to continuous *Z*?

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  - Better tensor decomposition methods for step 1?
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- We have a trajectory in N, p, and K.
  - Wang and Blei (2019) and Grimmer et al. (2020) require either  $p = \infty$  or  $N = \infty$ .
  - How: Tolerating mislabeled  $\hat{Z}$  and carrying error forward.
  - Plausibility: We allow K to increase with p.

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  - How: Tolerating mislabeled  $\hat{Z}$  and carrying error forward.
  - Plausibility: We allow K to increase with p.
- Compare to semiparametric regression  $Y = \hat{\beta}_j X_j + g(\hat{f}(X))$ .
  - Conditional independence restricts the function class for f in a principled way.
  - This drastically reduces the variance of  $\hat{\beta}$ .

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